<u>Chapter 7:</u> Linear Transformations

Ideas in this section...

- 1) Definition and examples of linear transformations
- 2) Some properties of Linear Transformations
- 3) Kernel and Image of a linear transformation
- 4) Examples of Kernel and Image of a linear transformation
- 5) Rank Nullity Theorem
- 6) Isomorphisms

Definition and Examples of Linear Transformations

<u>Def</u>: If *V* and *W* are 2 vectors spaces, a function $T: V \rightarrow W$ is called a linear transformation if

1)
$$T(\vec{v}_1 + \vec{v}_2) = T(\vec{v}_1) + T(\vec{v}_2)$$
 for all $\vec{v}_1, \vec{v}_2 \in V$

2) $T(r\vec{v}) = r T(\vec{v})$ for all $\vec{v} \in V$ and $r \in \mathbb{R}$

Definition and Examples of Linear Transformations

<u>Ex 1</u>: Show that the following are linear transformations...

a)
$$T: M_{22} \to P_2$$
 given by $T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = c + (b+d)x^2$

b) If
$$a \in \mathbb{R}$$
, $E_a: P_n \to \mathbb{R}$ given by $E_a(p(x)) = p(a)$

c)
$$D: P_n \to P_{n-1}$$
 given by $D(p(x)) = p'(x)$

Some Properties of Linear Transformations

Theorem 7.1.1

Let $T: V \to W$ be a linear transformation.

1. T(0) = 0.

2. $T(-\mathbf{v}) = -T(\mathbf{v})$ for all \mathbf{v} in V.

3. $T(r_1\mathbf{v}_1 + r_2\mathbf{v}_2 + \dots + r_k\mathbf{v}_k) = r_1T(\mathbf{v}_1) + r_2T(\mathbf{v}_2) + \dots + r_kT(\mathbf{v}_k)$ for all \mathbf{v}_i in *V* and all r_i in \mathbb{R} .

Kernel and Image of a Linear Transformation

<u>Def</u>: Let *V* and *W* be vector spaces and let $T: V \rightarrow W$ be a linear transformation. Then the kernel of *T* and the image of *T* are defined by...

$$\ker T = \{ \vec{v} \in V \mid T(\vec{v}) = \vec{0} \}$$

 $im T = \{ T(\vec{v}) \mid \vec{v} \in \mathbb{R} \}$

Kernel and Image of a Linear Transformation

Theorem 7.2.1

Let $T: V \to W$ be a linear transformation.

- 1. ker T is a subspace of V.
- 2. im T is a subspace of W.

Examples of Kernel & Image of a Linear Transformation

Ex 2: Find the kernel and image of each of these linear transformations...

a)
$$T: M_{22} \to P_2$$
 given by $T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = c + (b+d)x^2$

b) If $a \in \mathbb{R}$, $E_a: P_n \to \mathbb{R}$ given by $E_a(p(x)) = p(a)$

c) $D: P_n \to P_{n-1}$ given by D(p(x)) = p'(x)

Examples of Kernel & Image of a Linear Transformation

<u>Ex 2</u>: Find the kernel and image of each of these linear transformations...

b) If $a \in \mathbb{R}$, $E_a: P_n \to \mathbb{R}$ given by $E_a(p(x)) = p(a)$

Examples of Kernel & Image of a Linear Transformation

<u>Ex 2</u>: Find the kernel and image of each of these linear transformations...

c) $D: P_n \to P_{n-1}$ given by D(p(x)) = p'(x)

Rank – Nullity Theorem

<u>Def</u>: Let *V* and *W* be vector spaces and let $T: V \rightarrow W$ be a linear transformation. Then the <u>rank of *T*</u> and the <u>nullity of *T*</u> are defined by...

 $\operatorname{nullity}(T) = \operatorname{dim}(\ker T)$

 $rank(T) = \dim(im T)$

<u>Recall</u>: If A is an $m \times n$ matrix, we can define a linear transformation $T: \mathbb{R}^n \to \mathbb{R}^m$ by $T(\vec{x}) = A\vec{x}$. Then...(kernel, image, dimensions, rank-nullity)

Rank – Nullity Theorem

<u>Thm (Rank-Nullity Theorem)</u>: Let *V* and *W* be vector spaces and let $T: V \rightarrow W$ be a linear transformation. Assume ker *T*, *im T*, and *V* are finite dimensional. Then...

dim(im T) + dim(ker T) = dim Vor rank(t) + nullity(t) = dim V

<u>Def</u>: A function $T: V \to W$ is <u>one-to-one</u> if... $\forall \vec{v}_1, \vec{v}_2 \in V$, if $T(\vec{v}_1) = T(\vec{v}_2)$, then $\vec{v}_1 = \vec{v}_2$ Meaning...

<u>Def</u>: A function $T: V \to W$ is <u>onto</u> if... $\forall \ \vec{w} \in W$, $\exists \ \vec{v} \in V$ such that $T(\vec{v}) = \vec{w}$

Meaning...

- <u>Def</u>: A function $T: V \to W$ is an <u>isomorphism</u> if...
- 1) *T* is a linear transformation,
- 2) *T* is one-to-one, and
- 3) T is onto
- Meaning...

<u>Thm</u>: A linear transformation $T: V \to W$ is one-to-one if and only if ker $T = \{ \vec{0} \}$

<u>Ex 3</u>: Show that the following linear transformations are isomorphisms...

a) $T: \mathbb{R}^2 \to P_1$ defined by T(a, b) = a + bx

b)
$$T: M_{22} \to P_3$$
 defined by $T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = c + ax + (a + b)x^2 + 2dx^3$

What you need to know from the book

Book reading

Sec. 7.1: pg. 375 – top half of 378 Sec. 7.2: pg. 382 – 387 Sec. 7.3: pg. 392

Problems you need to know how to do from the book

Sec. 7.1: #'s 1-3, 6, 8-9, 15, 17 Sec. 7.2: #'s 1-4, 6-11, 14-15 Sec. 7.3: #'s 1